



Universitat
Pompeu Fabra
Barcelona

Robust Service Orchestration for Computing Continuum Systems

Boris Sedlak



Co-funded by
the European Union



Funded by
the European Union
NextGenerationEU



Plan de Recuperación,
Transformación y Resiliencia

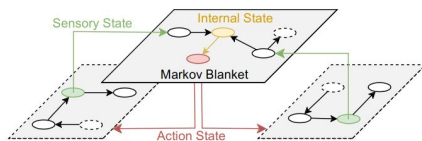
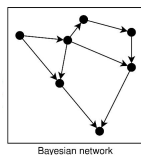
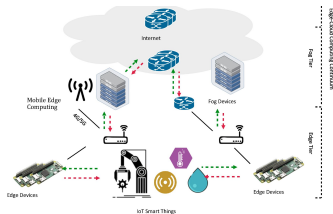


Abstract

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While the emergence of Edge computing promises major improvements in IoT processing, the heterogeneity and volatility of Edge infrastructures make service orchestration increasingly complex. Yet, to maintain robust system operation, we must be certain—or at least certain enough—about the expected outcome of our actions, such as shifting resources or workloads. This talk highlights Active Inference (AIF), an agent-based framework inspired by neuroscience, which supports operators in developing a causal understanding of the underlying generative processes. By continuously exploring and interacting with their environment, AIF agents develop models of the systems they govern and their interdependencies. This, in turn, enables them to predict the outcomes of actions when composing systems into larger architectures. The talk first outlines how AIF, as a concept, is inherently designed for acting under uncertainty, and then presents examples of how AIF can establish robust understanding of the environment to ensure continuous and adaptive system operation.

Structure of the Talk



Motivation &
Common Problems

Methodologies &
Latest Results

Future Work



I – Who am I ??

Boris Sedlak

Postdoc @ UPF Barcelona

Distributed Intelligence & Systems-Engineering Lab

PhD @ TU Wien, Vienna

Distributed Systems Group

Software Engineer @ Lotterien

Agile Development and Testing

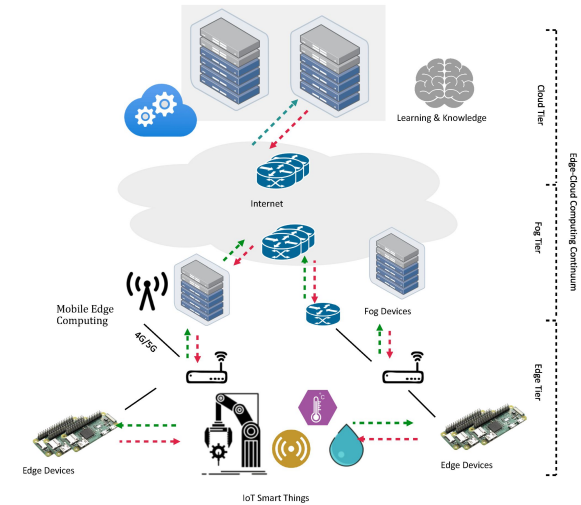


I – Common Concepts

Computing Continuum (CC) as a composition of multiple processing tiers that stretch from IoT and edge computing, over Fog resources, to distant Cloud centers

Combines the benefits of all its tiers, i.e., low-latency and privacy-protecting computation from Edge, high availability and virtually unlimited processing resources from Cloud

Smart Cities are a common instance of distributed systems, where interconnected services (e.g., traffic surveillance or road surveillance) collaborate based on collected sensor data



Example of a Computing Continuum architecture [1]

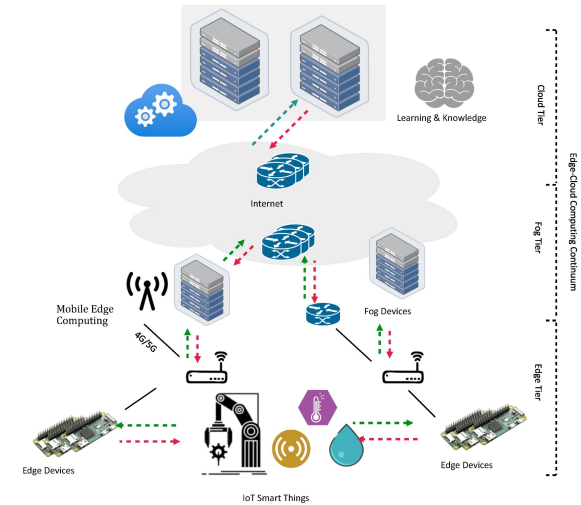
[1] P. Donta, I. Murturi, V. Casamayor, B. Sedlak, and S. Dustdar; **Exploring the Potential of Distributed Computing Continuum Systems** (2023)

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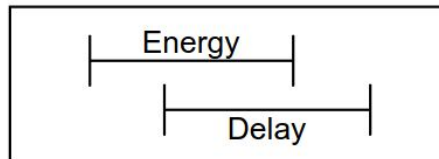


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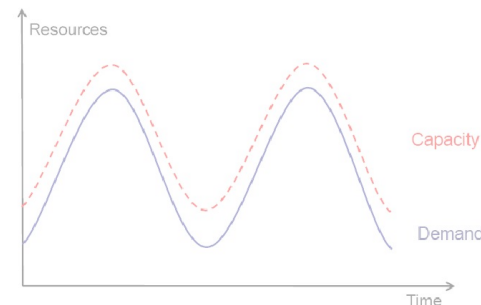
I – Common Concepts (cont.)

Service Level Objectives (SLOs) specify requirements that must be ensured throughout operation (e.g., latency < t).



Elasticity Strategies scale a system according to current demand; e.g., if performance is insufficient, allocate more resources. However, what if this does not fulfill SLOs?

Service Level Agreements (SLAs) as binding agreement between service provider and consumer. However, very limited support in resource-restricted environments



Elasticity allocates the right amount of resources [2]

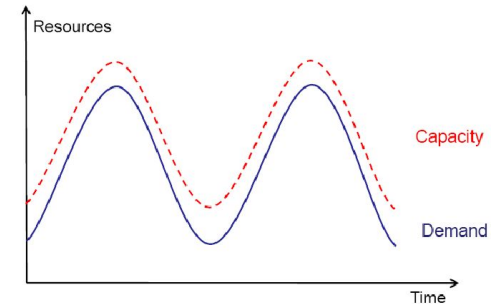
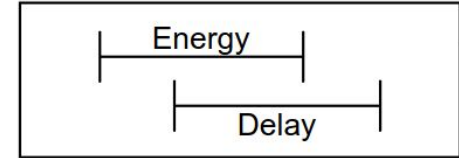
[2] Ricciardi et al., **Saving Energy in Data Center Infrastructures** (2011)

I – Common Concepts (cont.)

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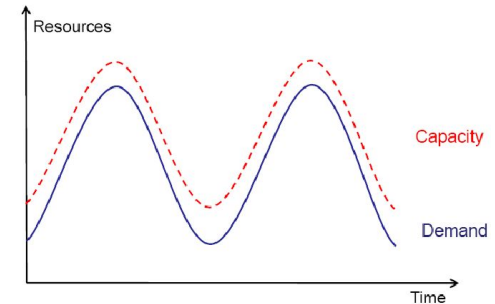
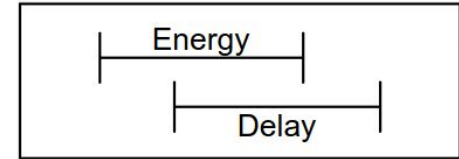
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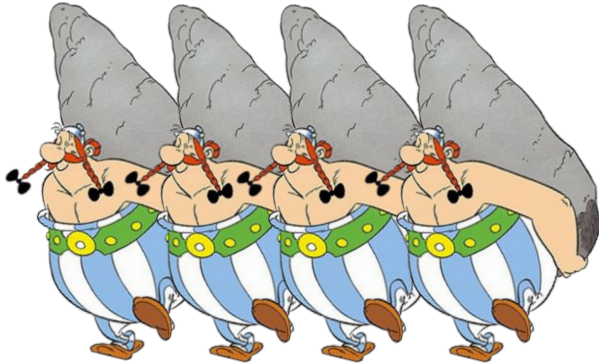
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I – Fundamental Problems



Homogeneous Resources (Cloud)

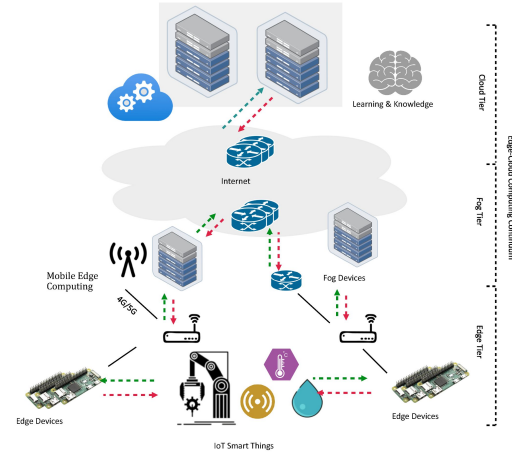


Heterogeneous Resources (CC)

I – Fundamental Problems



Homogeneous Resources (Cloud)

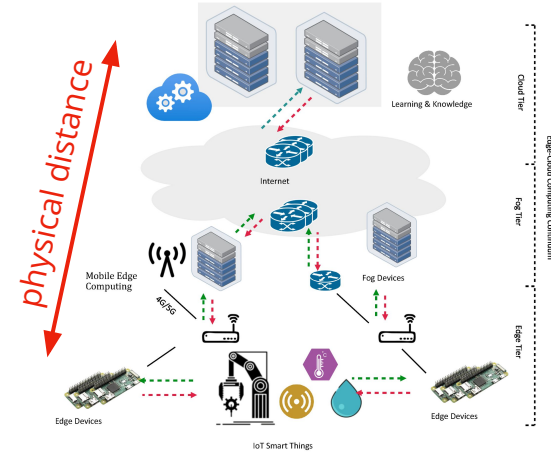


Heterogeneous Resources (CC)

I – Fundamental Problems



Homogeneous Resources (Cloud)

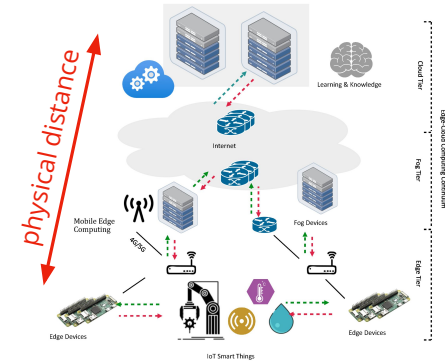


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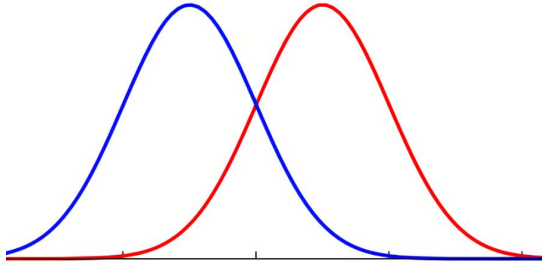
I – Fundamental Problems

Heterogeneity prevents simple task distribution between available devices. Don't know a priori what will be the *behavior* of service X on device Y

Physical distribution creates latency between different distributed devices; transferring state information (e.g., CPU load) creates lots of traffic on the network.



I – Fundamental Problems (cont.)



System dynamics change over time



Low trust into black-box models

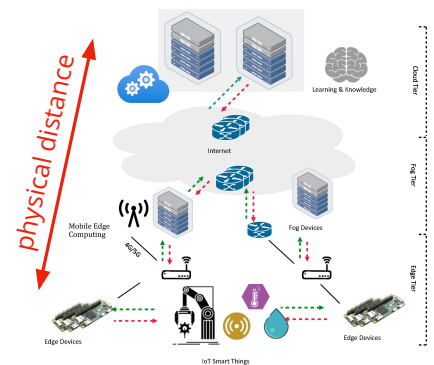
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Variable drifts cause any ML model to lose accuracy over time. Cannot train models in one-shot operations but must incorporate changes continuously.

Low-trust into black-box ML models that cannot give human-verifiable chains of thought. E.g., debugging



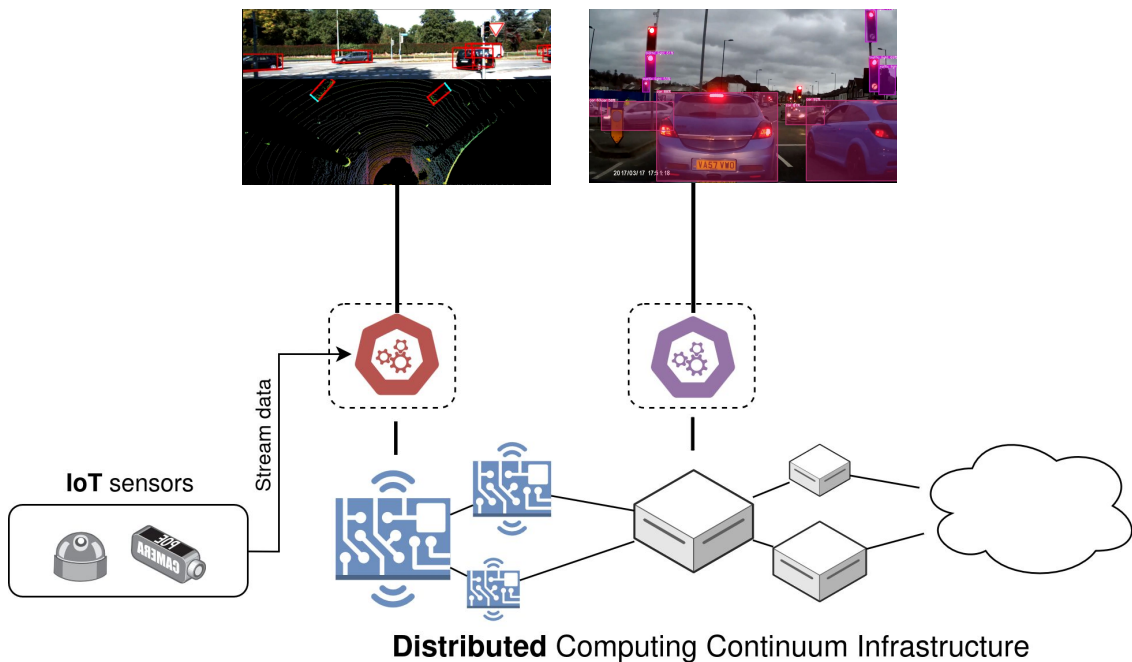


I – Overview of our Approach

Hidden in main presentation

Distributed processing

- Distributed CC infrastructure composed of various **device types** at different **locations**
- Sensor data continuously streamed from IoT devices to different processing services

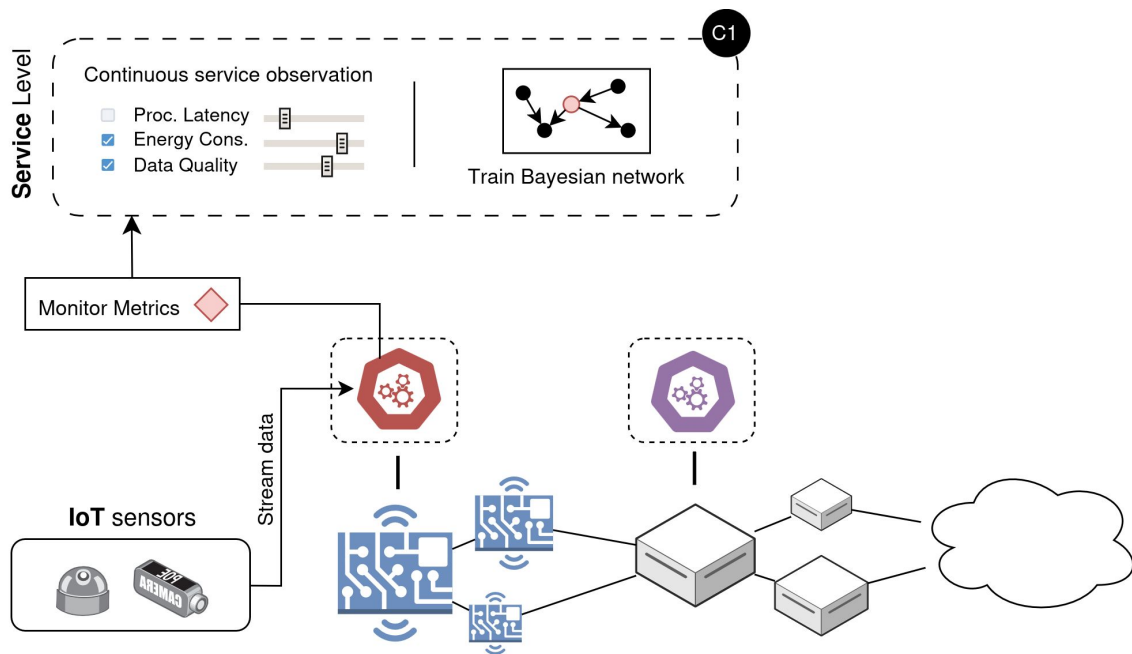




I – Overview of our Approach (C1) **Hidden in main presentation**

Service interpretation

- Monitor processing across CC by collecting metrics; eval. real-time SLO fulfillment
- Train a model (i.e., BN) for predicting SLO fulfillment of **individual** services in different deployment configurations [7]
- Retrain model according to SLO prediction accuracy; slows down as model improves [9]

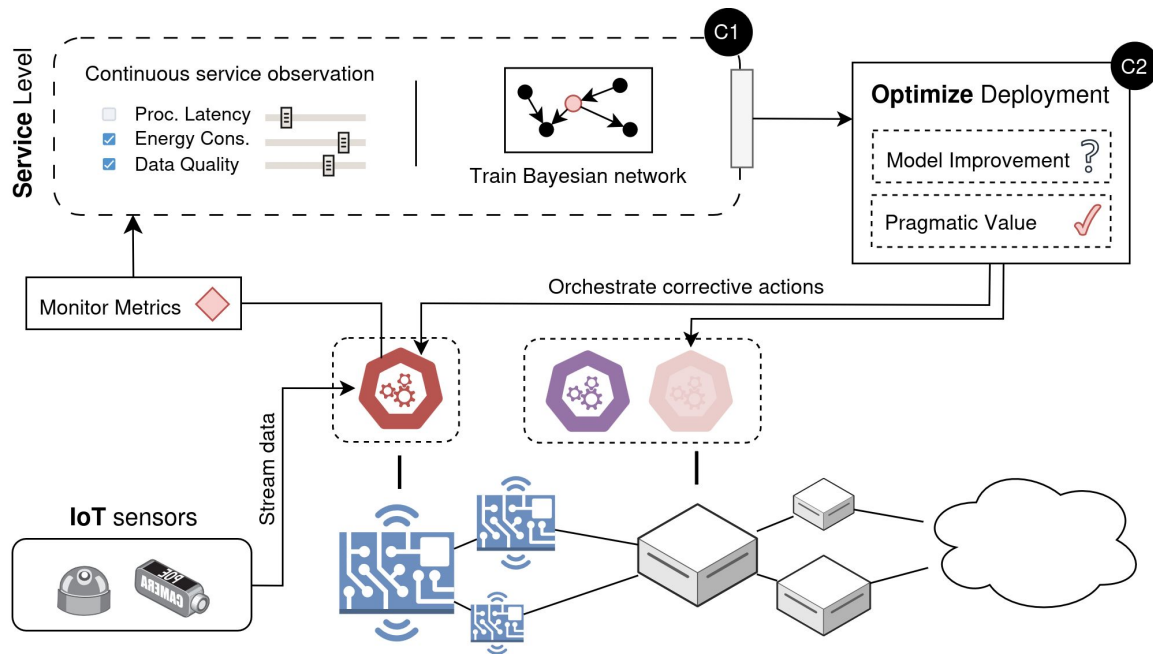


[7] Sedlak et al., **Designing Reconfigurable Intelligent Systems with Markov Blankets**, at ICSOC 2023

[9] Sedlak et al., **SLO-Aware Task Offloading Within Collaborative Vehicle Platoons**, at ICSOC 2024

Service adaptation

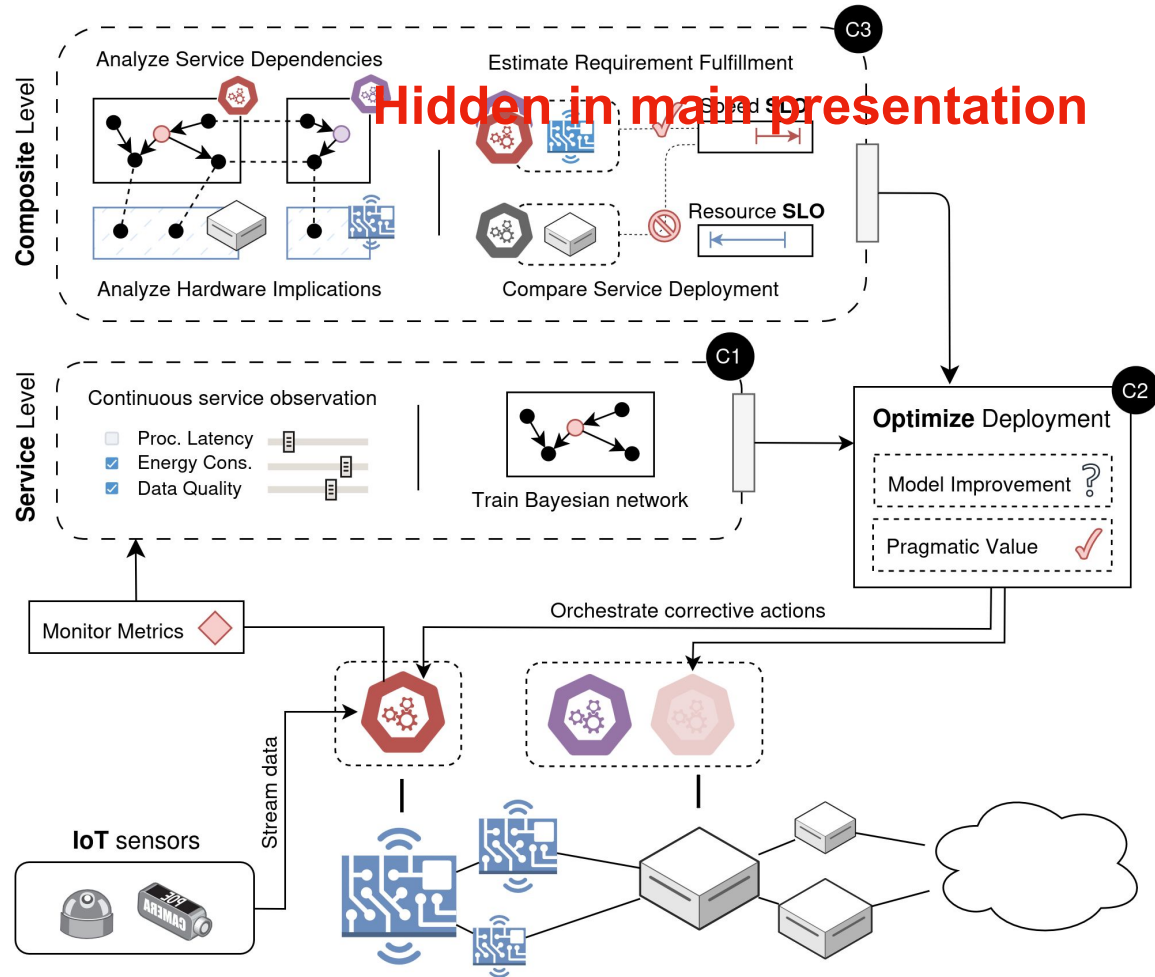
- Optimize **local SLO fulfillment** by reconfiguring processing services; choose between avail. elasticity strategies [5]
- Escape local optima through continuous exploration; check poss. **model improvement** [12]
- Decisions can be empirically verified and interpreted; useful for non-technical explanation



I – Overview of our Approach (C3)

Service collaboration

- Compose individual models to overarching representation; quantify service dependencies and **impact on hardware** [4]
- Collaborative orchestration considers service relations to optimize global SLO fulfillment
- Exchanging and merging BNs between services to speed up the **onboarding** of new service types or devices types [13]



[4] Sedlak et al., **Markov Blanket Composition of SLOs**, at IEEE Service EDGE 2024

[13] Sedlak et al., **Equilibrium in the Computing Continuum through Active Inference**, at Elsevier FGCS, 2024

I – Fundamental Problems (cont.)

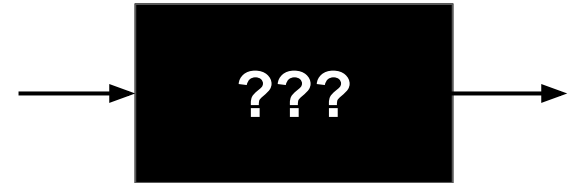
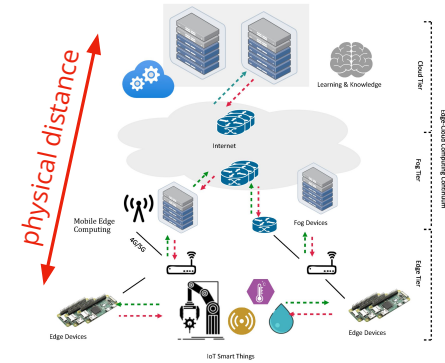
Heterogeneity prevents simple task distribution between available devices. Don't know a priori what will be

Decentralized decision-making based on local observations and understanding

Physical distribution of devices (e.g., CPU load) creates lots of traffic on the network.

Variable drifts cause any ML model to lose accuracy over time. Cannot train models in one-shot operations but must incorporate changes continuously.

Low-trust into black-box ML models that cannot give human-verifiable chains of thought. E.g., debugging



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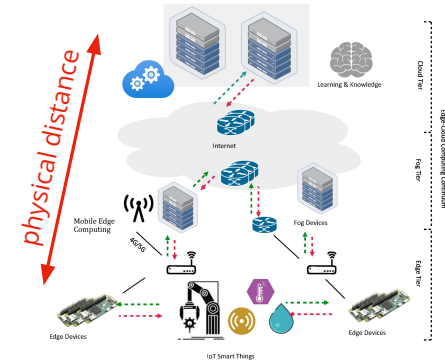
Decentralized decision-making based on local observations and understanding

Physical distance (e.g., network latency, CPU load) creates lots of traffic on the network.

Variability of tasks and environments over time and space, but machine learning is not designed for this.

Continuous and lifelong learning of environment, verifiable through structural causal models

Low-level human-verifiable chains of thought. E.g., debugging

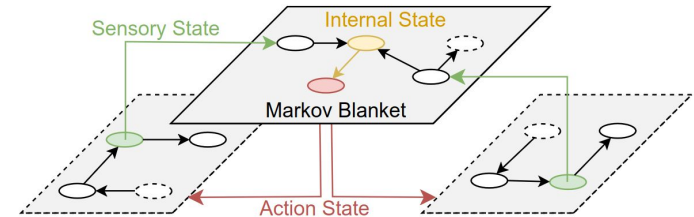
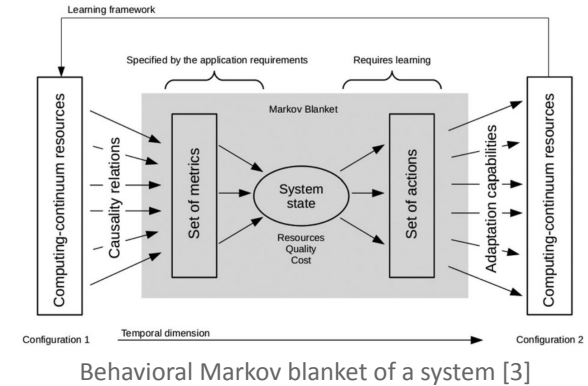


II – Markov Blanket (MB)

Interactions between **systems** (e.g., human in world) can be expressed through MBs; fulfill Markov property – so decisions can be taken based on system's current state

Creates **formal boundary** between a system and external states; within MB, discard all variables that show no impact on internal states and requirements (i.e., SLO fulfillment)

Provides clear interfaces for **sensory** and action **states**; policy (e.g., scaling) as a mapping between these states



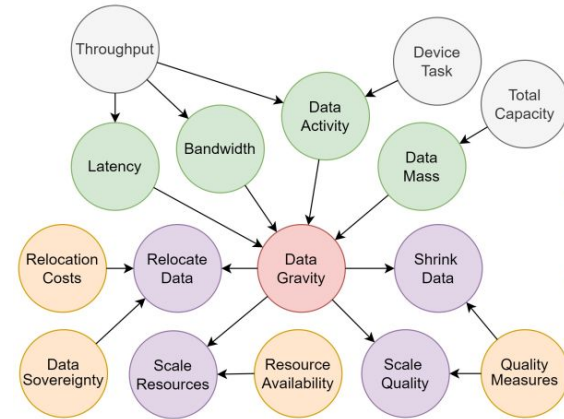
[3] Dustdar et al., **On Distributed Computing Continuum Systems** (2023)

[4] Sedlak et al., **Markov Blanket Composition of SLOs**, at IEEE Services Edge 2024

MB: Expresses how to evaluate a composite SLO and how to react according to the current device context

Behavioral model

Internal state (●) evaluates objectives and how these relate to external sensory inputs (●); can interact with the world through action, i.e., elasticity strategies (●), which are influenced by contextual factors (●)



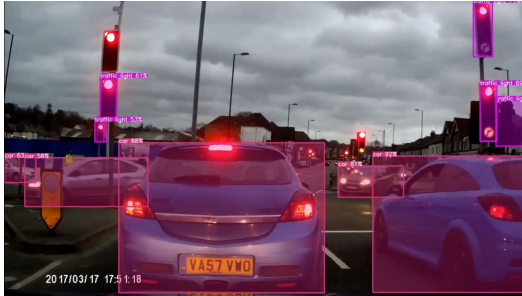
Example of a behavioral model for data gravity [5]

[5] Sedlak et al., **Controlling Data Gravity and Data Friction: From Metrics to Multidimensional Elasticity Strategies**, at IEEE Service EDGE 2023

II – Stream Processing Scenarios

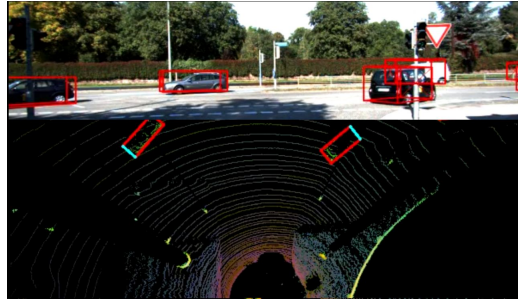
Commonly addressed use cases revolve around continuous **stream processing**; in case **time-critical** adaptations are required, this poses a higher need for sophisticated adaptation mechanisms.

Video Processing (Yolo V8)



Object detection in a video stream using Yolo [6]

Mobile Mapping (Lidar)



Creating a mobile map from binaries using Lidar [6]

QR Scanner (OpenCV)

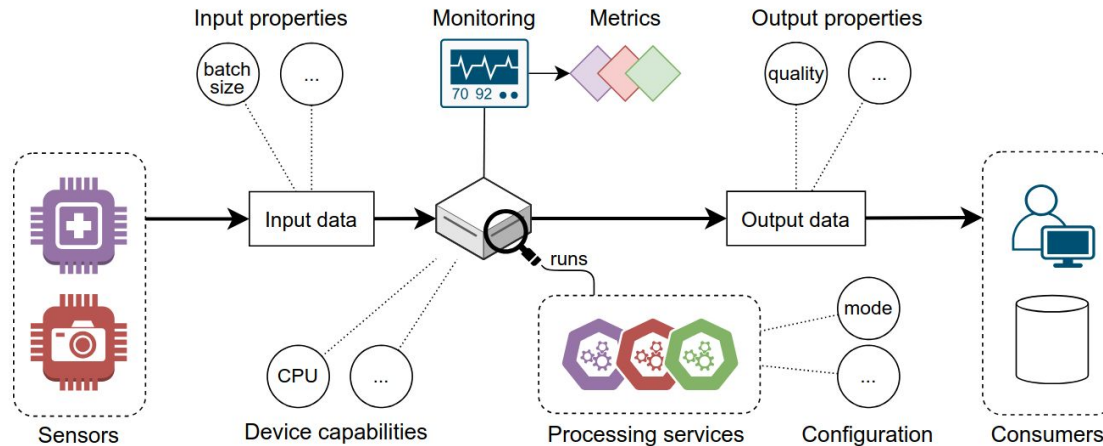


QR code scanning in a video using OpenCV [6]

[6] Sedlak et al., **Adaptive Stream Processing on Edge Devices through Active Inference** (Scheduled for 2025 at Springer ES)

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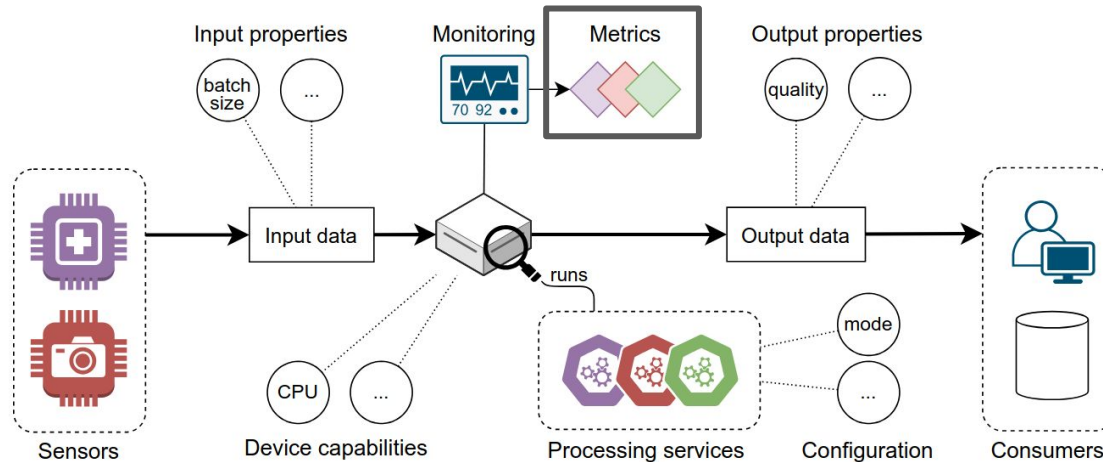


Abstract representation of a monitored stream processing service [6]

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Abstract representation of a monitored stream processing service [6]

fps	pixel	cores	change_flag	timestamp
31	800	3	False	2024-11-30
32	800	3	False	2024-11-30
32	800	3	False	2024-11-30
32	800	3	False	2024-11-30
32	800	3	False	2024-11-30
30	800	3	False	2024-11-30
32	800	3	False	2024-11-30
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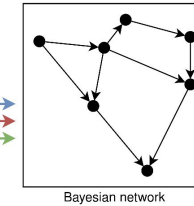
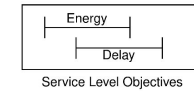
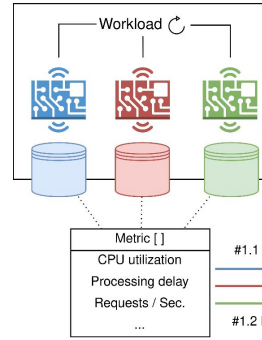
Example of processing metrics as tabular data [6]

[6] Sedlak et al., **Adaptive Stream Processing on Edge Devices through Active Inference** (Scheduled for 2025 at Springer ES)

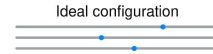
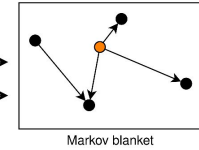
Optimize the system (i.e., its SLO fulfillment) according to model

Model: use processing metrics and properties to train a *generative model* that describes the variable relations within the environment.

1. Bayesian Network Learning



2. Markov Blanket Selection



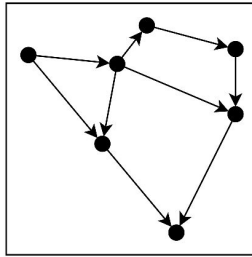
Probability of SLO violations

3. Explainable Inference

[7]

[7] Sedlak et al., **Designing Reconfigurable Intelligent Systems with Markov Blankets**, at ICSOC 2023

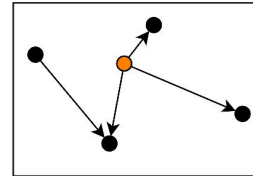
Bayesian Network Learning



Bayesian network

- ❑ **Structure Learning**
Various algorithms (e.g., HCS)
Directed Acyclic Graph (DAG)
- ❑ **Parameter Learning**
Various algorithms (e.g., MLE)
Conditional Prob. Table (CPT)

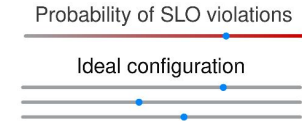
Markov Blanket Selection



Markov blanket

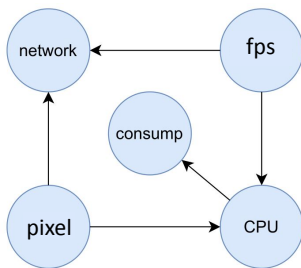
- ❑ **Causality filter**
Extract subset of variables
that impact SLO fulfillment
- ❑ **Behavioral MB**
MB now contains contextual
factors & elasticity strategies

Knowledge Extraction



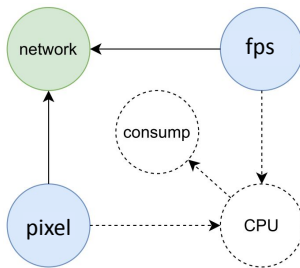
- ❑ **Conditional Inference**
Estimate impact of different
deployment configuration
- ❑ **Optimize SLOs**
Adjust processing services
according to inferred policy

Bayesian Network Learning



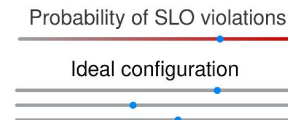
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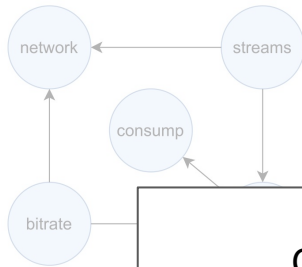
Knowledge Extraction



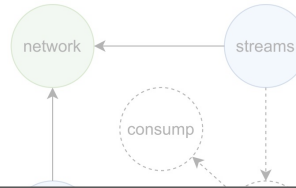
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II – Basic Methodology

Bayesian Network Learning



Markov Blanket Selection



Knowledge Extraction



Core methodology applied in multiple application.



Structure Learning

Various algorithms (e.g., HCS)
Directed Acyclic Graph (DAG)



Parameter Learning

Various algorithms (e.g., MLE)
Conditional Prob. Table (CPT)



Causality Inter

Extract subset of variables
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Behavioral MB

MB now contains contextual
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Conditional Inference

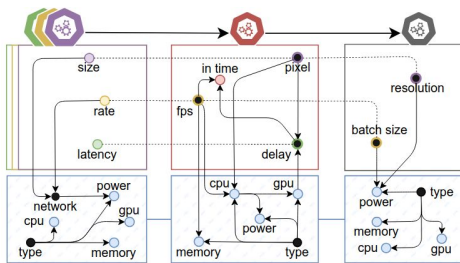
Estimate impact of different
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Optimize SLOs

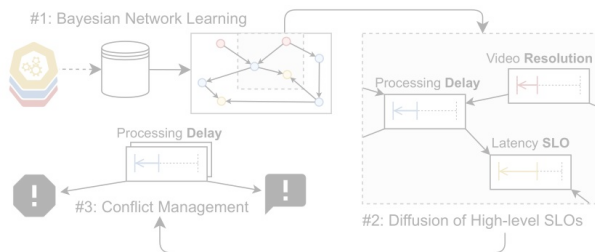
Adjust processing services
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Transitive Requirements [4]



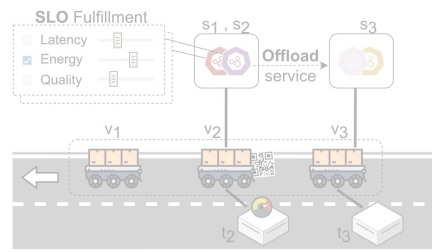
Optimize SLO fulfillment by
deploying microservices over
heterogeneous hardware;
use BNs to analyze & optimize
service/device dependencies

Diffusing High-Level SLOs [8]



Find configurations for subsystems
according to **high-level SLO** values;
create hierarchy of dependencies
and infer lower-level configurations

SLO-Aware Offloading [9]



Offload microservices over
heterogeneous hardware;
estimate effects of service
swapping on SLO fulfillment

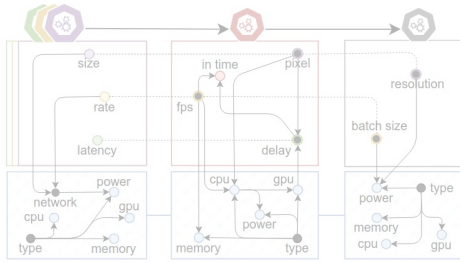
[4] Sedlak et al., **Markov Blanket Composition of SLOs**, at IEEE Services EDGE 2024

[8] Sedlak et al., **Diffusing High-level SLO in Microservice Pipelines**, at IEEE SOSE 2024

[9] Sedlak et al., **SLO-Aware Task Offloading Within Collaborative Vehicle Platoons**, at ICSOC 2024

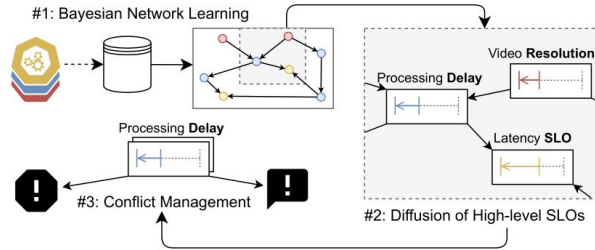
II – Multiple Applications

Transitive Requirements [4]



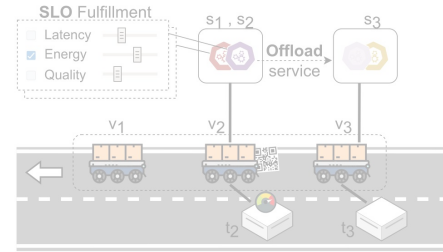
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swapping on SLO fulfillment

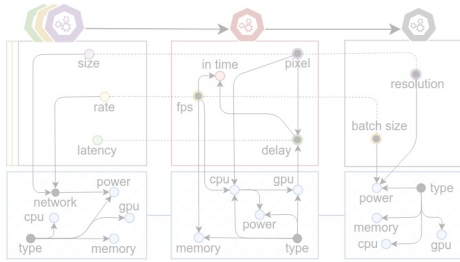
[4] Sedlak et al., **Markov Blanket Composition of SLOs**, at IEEE Services EDGE 2024

[8] Sedlak et al., **Diffusing High-level SLO in Microservice Pipelines**, at IEEE SOSE 2024

[9] Sedlak et al., **SLO-Aware Task Offloading Within Collaborative Vehicle Platoons**, at ICSOC 2024

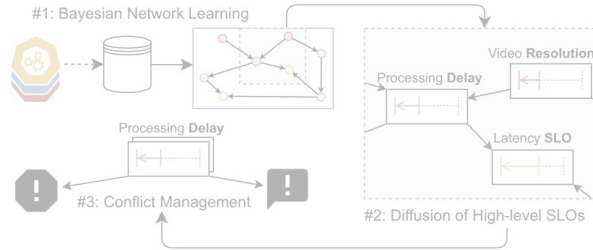
II – Multiple Applications

Transitive Requirements [4]



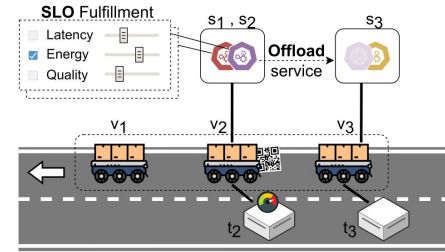
Optimize SLO fulfillment by
deploying microservices over
heterogeneous hardware;
use BNs to analyze & optimize
service/device dependencies

Diffusing High-Level SLOs [8]



Find configurations for subsystems
according to **high-level SLO** values;
create hierarchy of dependencies
and infer lower-level configurations

SLO-Aware Offloading [9]



Offload microservices over
heterogeneous hardware;
estimate effects of service
swapping on SLO fulfillment

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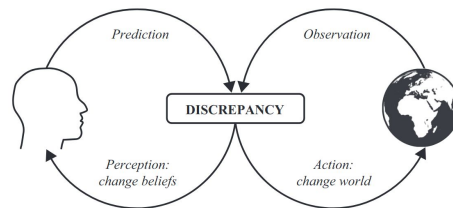
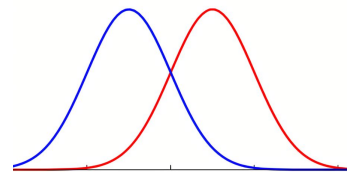
[9] Sedlak et al., **SLO-Aware Task Offloading Within Collaborative Vehicle Platoons**, at ICSOC 2024

Known Shortcomings

- (1) BNL requires large amounts of training data upfront
- (2) can't visit all possible states, so where to start exploring?
- (3) over time, models get distorted due to variable drifts

Active Inference

Concept from **neuroscience** developed by Friston et al. [10,11]; allows agents to interact with their environment by learning the underlying **generative models** to persist over time



Action-perception cycle in Active Inference [11]

[10] Parr et al., **Active Inference: The Free Energy Principle in Mind, Brain, and Behavior** (2022)

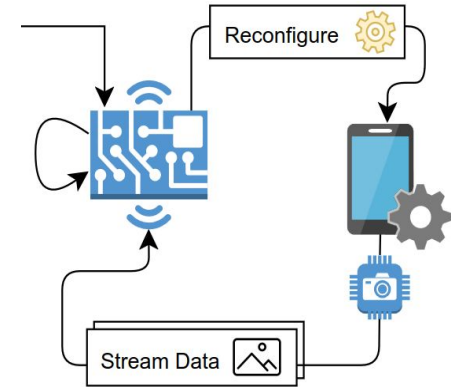
[11] Friston et al., **Designing ecosystems of intelligence from first principles** (2024)

II – Active Inference in CC Systems

Mapping between neuroscience and distributed computing systems [6,12,13]; understanding processing requirements (i.e., SLOs) as a form of **homeostasis**, e.g., cell temperature

Create autonomous components that identify how to ensure requirements and resolve them independently, clear modelling between higher-level and low-level components

Simplify service orchestration in large-scale distributed systems; decentralized decision-making of individual components **avoids** transferring service states to the Cloud



Ensure internal requirements [13]

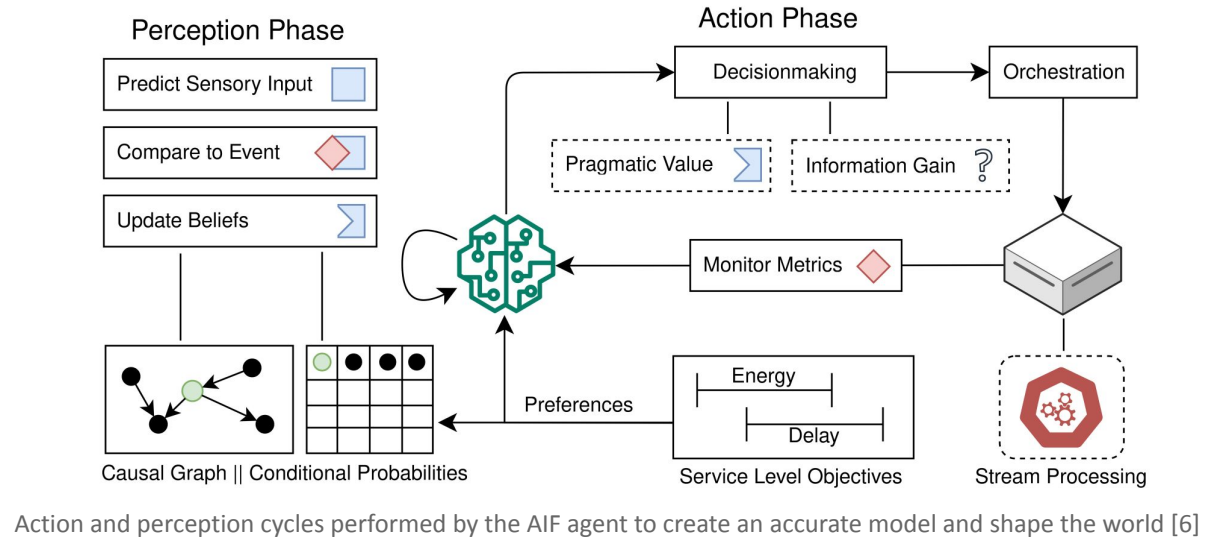
[6] Sedlak et al., **Adaptive Stream Processing on Edge Devices through Active Inference** (Scheduled for 2025 at Springer ES)

[12] Sedlak et al., **Active Inference on the Edge: A Design Study**, at PerconAI 2024

[13] Sedlak et al., **Equilibrium in the Computing Continuum through Active Inference**, Elsevier FGCS (2024)

Approach

- (1) **Specify** ideal runtime behavior through SLOs
- (2) **AIF agents** monitor their environment & collect metrics
- (3) **Perception phase** predicts expected SLO fulfillment and adjusts the generative model
- (4) **Action phase** orchestrates the processing environment to optimize both SLOs and model



[6] Sedlak et al., **Adaptive Stream Processing on Edge Devices through Active Inference** (Scheduled for 2025 at Springer ES)

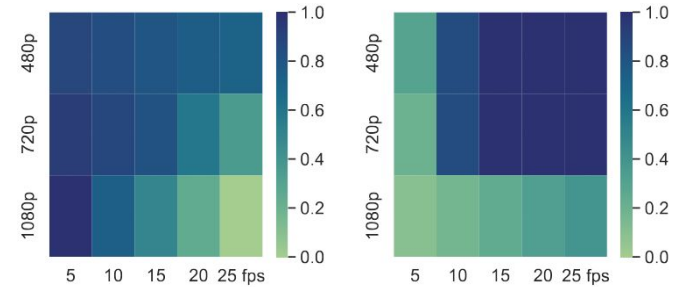
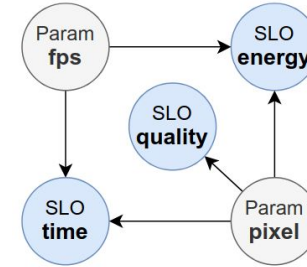
II – Active Inference Architecture (cont.)

Interpretable behavior [6]

- Empirically verify variable relations in the BNs, e.g., increasing quality (pixel) leads to high energy usage; adjust **parameters** (i.e., pixel & fps) according to SLOs
- Quantified preferences of the agent: (1) expected SLO fulfillment or (2) potential model improvement; determine the behavior of the scaling agent

Continuous composition [4]

- Gradually create increasingly accurate models for individual processing services; continuously compose to estimate the **impact** they have on each other



(b) Pragmatic value

(c) Information gain

[4] Sedlak et al., **Markov Blanket Composition of SLOs**, at IEEE Services EDGE 2024

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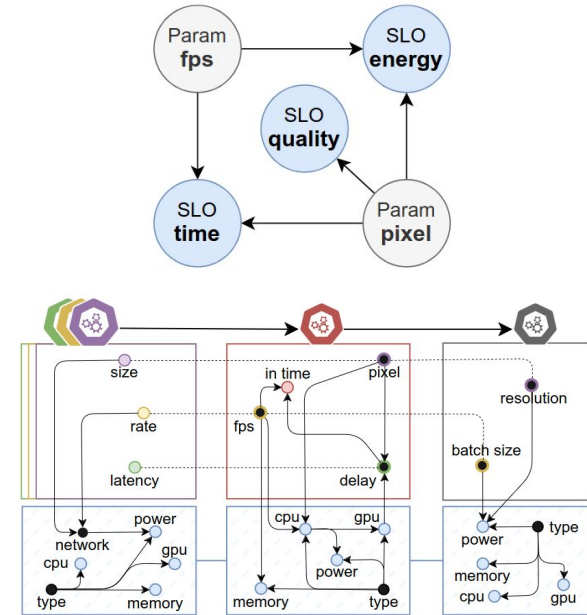
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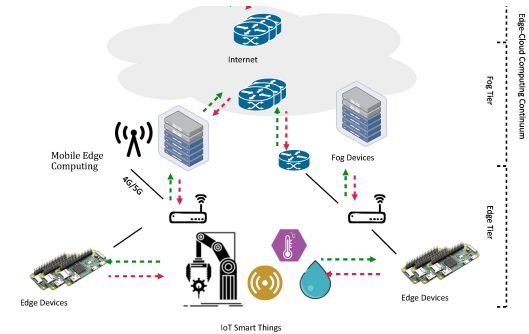
[6] Sedlak et al., **Adaptive Stream Processing on Edge Devices through Active Inference** (Scheduled for 2025 at Springer ES)

III – Summary Contemporary Challenges

IoT & Edge enable large-scale distributed services that optimize our daily routines; CC as underlying infrastructure for supporting these services

Resource limitations and device heterogeneity complicate service orchestration; device & service behavior not guaranteed, leads to violated SLOs

Missing explainability for black box ML models; leads to low trust and non-interpretable behavior

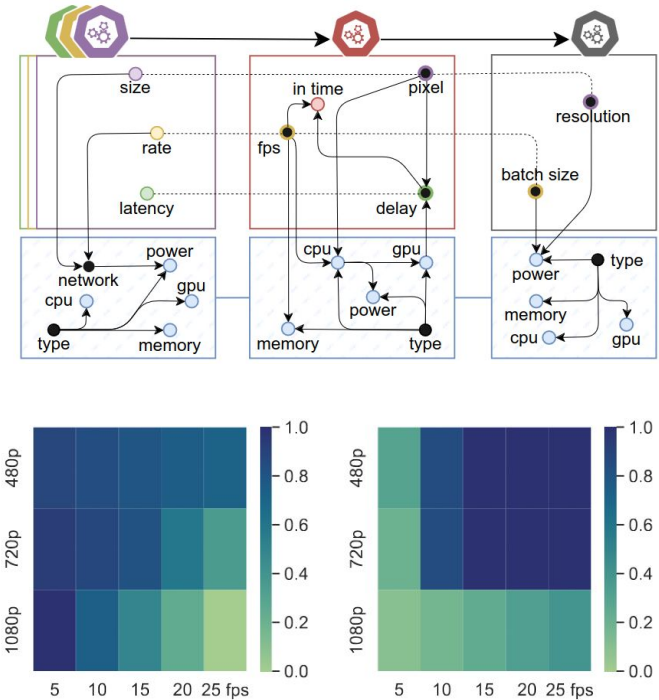


III – Summary Contributions & Results

Monitor processing services closely, analyze their behavior, and infer optimal elasticity strategy; train a MB that combines all these factors in one model

Dynamically optimize SLOs fulfillment for a network of processing services and heterogeneous devices; orchestrate services (i.e., placement, configuration, replication, etc) according to current context

Active Inference as a natural fit to train behavioral MBs and keep them accurate; balance continuously between ensuring SLOs and improving the model



III – Summary Limitations & Challenges (1/2)

High cost of running empirical experiments; slow training progress, needs training environment.

→ Train agents in simulated environments; creating accurate environment, like for **digital twinning**

Overhead of extracting baselines from publication; low rigor from generic algorithms, e.g., SB3

→ Support baseline comparison and standardized problem instances in evaluation environment

Governance limited to individual vendor; SLAs only supported by one provider and its subset of nodes
→ Create overarching models for orchestration and client compensation; technical & economical part

Active Inference for Digital Twins: Predicting and Optimising IoT Processing Service Performance

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Abstract
Digital Twins (DTs) are emerging as enablers for real-time monitoring and control in IoT systems. In this work, we propose a DT enabled with Active Inference (AI), a framework rooted in the Free Energy Principle, to enable DTs with predictive and decision-making capabilities. Our approach is evaluated on a realistic edge computing scenario where two co-located edge processing services—a computer vision pipeline using YOLOv8 and a QR code reader—compete for limited CPU resources. The DT continuously infers physical twin state, predicts future performance, and selects actions to meet Service Level Objectives (SLOs). In a series of experiments, we validate the predictive accuracy and control effectiveness of the AI-enabled DT. Notably, the DT achieves a cumulative SLO fulfillment above 80% for both services, and predicted throughput regression shows high alignment with real observations, confirmed through statistical testing.

CCS Concepts
• Computer systems organization → Real-time system architecture

Keywords
Digital Twins, Predictability, Active Inference, Internet of Things, IoT

 <https://doi.org/10.1145/3770691.3770692>
ACM Reference Format:
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1 Introduction
The fast advancement of technology over the last few decades has transformed the way systems are monitored, controlled, and optimised in diverse domains: from manufacturing and logistics to smart cities and healthcare. The rise of smart devices, Internet of Things (IoT), Artificial Intelligence (AI), and Cloud Computing have enabled the emergence of Digital Twins (DTs).
In large-scale and distributed IoT environments, such as smart manufacturing lines, intelligent transportation systems, or health care infrastructures, managing the complexity of the system becomes a fundamental challenge [15]. DTs provide a suitable way to monitor, model and manage these IoT systems by creating virtual replicas of physical entities operating under real-time data flows, enabling proactive and adaptive decision making [7].
The DT concept was originally coined by Griebl and Viktor in 2003 defined as the coexistence of three elements: (1) a physical space (i.e. virtual space), and (2) a bidirectional communication both spaces allowing their convergence [4]. Since then, the concept has evolved, currently, DTs are understood as dynamic virtual representations of physical entities that allow real-time monitoring, simulation, prediction, and control of the modelled entity/behaviour [4]. One of the main properties of a DT is the predictability [14], which refers to the ability of the DT to anticipate and improve the future behaviour of its physical twin [5]. This property is crucial to enable intelligent decision making within the DT, in particular when leveraging AI-based techniques.

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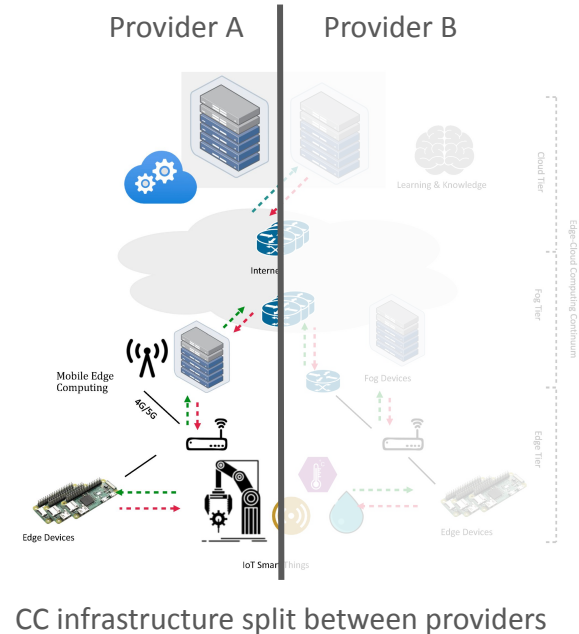
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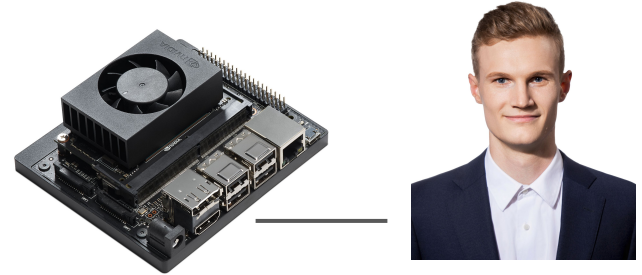
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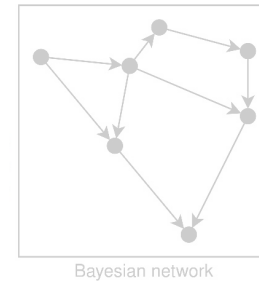
III – Summary

Limitations & Challenges (2/2)

Missing sovereignty over data processing; devices rarely in possession of service consumers
→ Integrate personal devices into infrastructure;
combine with personal wallets and trusted env.



Rigid inference quality for recommending actions;
prone to violate operational boundaries, e.g., time
→ Consider resources and context when inferring
actions, e.g., smaller graph; create **elastic certainty**

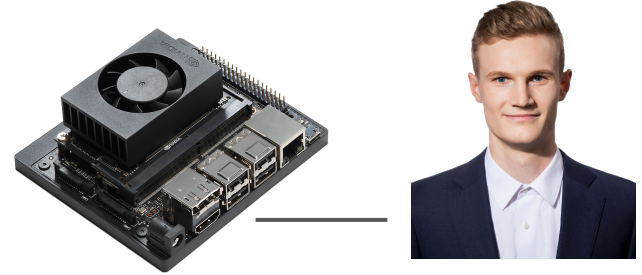


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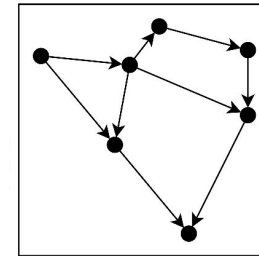
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Bayesian network